GPU offloading in the High Level Trigger of the KOTO experiment

Measurement System Workshop

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Overview

Contents

- Why GPUs in KOTO's High Level Trigger
- How we have re-written CPU code for massive parallelism on GPUs
- Performance comparison

Goal:

- To encourage you to consider using GPUs in your experiment
- To show how KOTO is planning on taking advantage of them

Towards heterogeneous Triggers in HEP

HEP experiments

- Thousands of independent events are readout every second
- Online event processing does not require complex calculations

A CPU server

 Tens of independent computing cores that can perform very complex tasks







 Millions of independent computing threads that can perform simple tasks









Heterogeneous Computing:

- CPUs are used together with accelerators (GPUs, etc)
- Each device performs the tasks it is best suited for

the KOTO experiment aims to measure the Branching ratio (BR) of $K_L^0 \longrightarrow \pi^0 \nu \bar{\nu}$

Theoretically predicted to be very small:

BR(
$$K_L^0 \longrightarrow \pi^0 \nu \bar{\nu}$$
) ~ 3×10^{-11}

Any small fluctuation from this value due to physics Beyond the SM can be easily observed experimentally

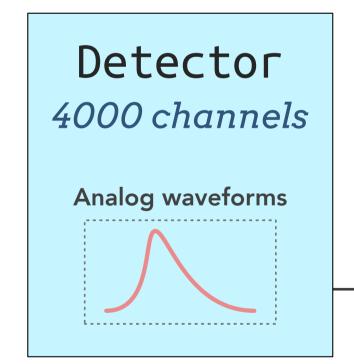
The Beam Intensity Upgrade

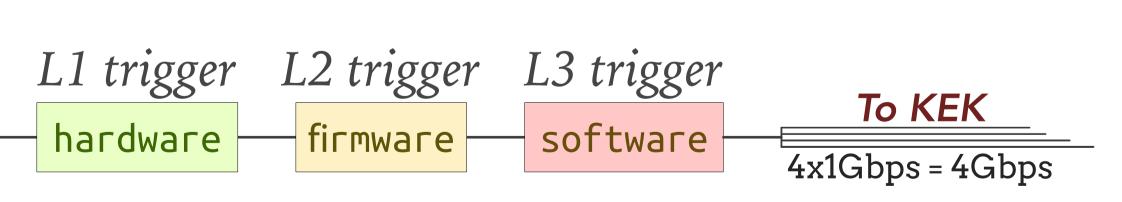
Ongoing beam intensity Upgrade at JPARC

64 kW→ 100 kW (near future)

Hoping to eventually reach 150 kW

- → Input data rate increases, KOTO's sensitivity improves faster
- → DAQ needs an upgrade to handle the expected input rate





The bandwidth to KEK is fixed and it is our main bottleneck

KOTO's data rates at the L3

Input from L2:

```
2300*[trig/s]*100[kW]/64[1/kW]*4000[wfms/trig]

* 16*64[bits/wfm] / 8/2**30[GiB/bit]

= 1.8 GiB/s (2.6 GiB/s assuming a 150 kW beam)
```

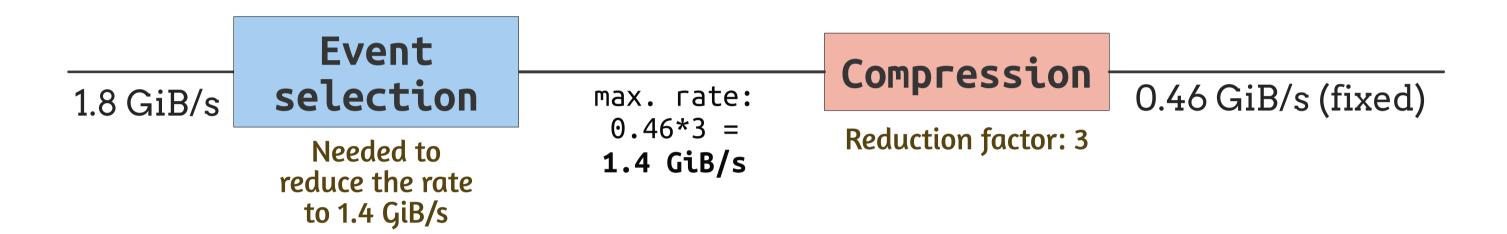
Output to KEK:

4[Gbps] = 0.46 GiB/s

Input/Output = 1.8/0.46 = 4

KOTO's data rates at the L3

- Data rate needs to be reduce by a factor of 4 at the L3
- We can get a factor of ~3 from waveform compression



Currently, compression is done in CPUs and there is little room for event selection

Option 1:

Buy more CPUs

Option 2:

Offload the compression stage to a GPU

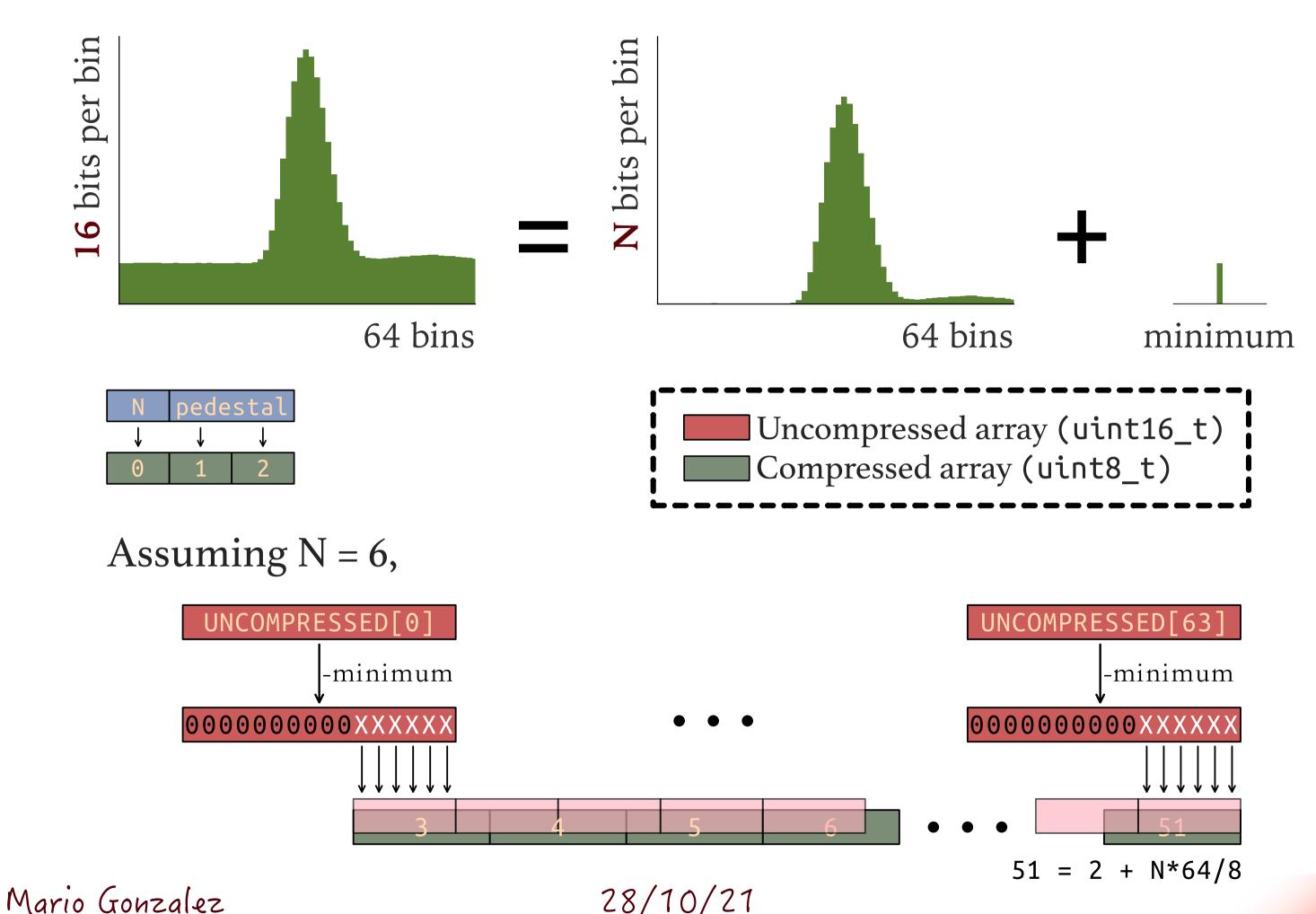
Requirements of the waveform compression

Maximum input rate: 1.4 GiB/s

This means we have:

- 1 s to compress 1.4 GiB
- 1 s to copy 1.4 GiB to/from the GPU

Waveform compression in the KOTO experiment



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The Challenge of doing compression on GPUs

```
for wfm in packet: ~1e7 wfms in a 1.4 GiB packet

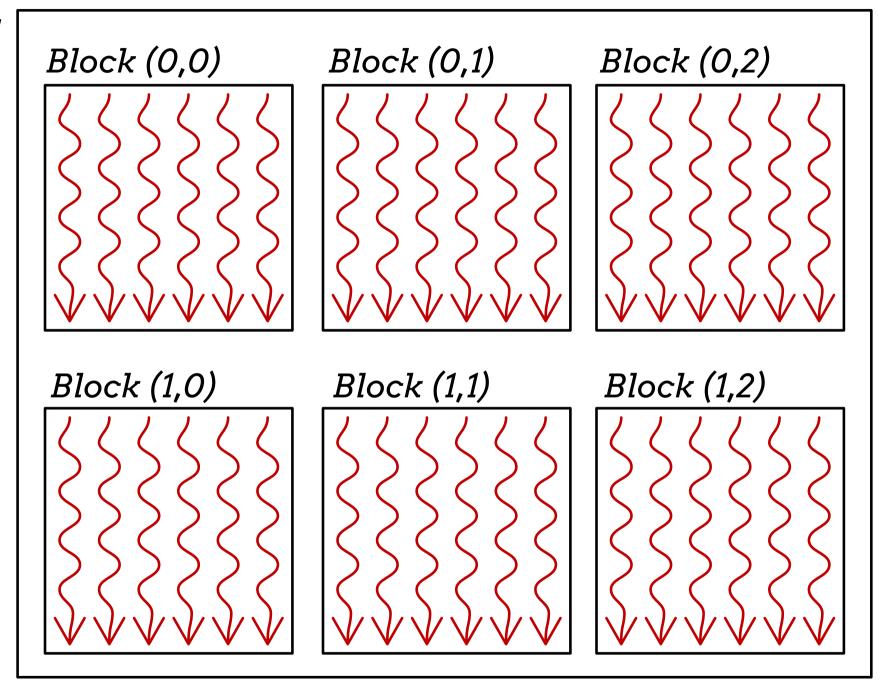
for bin in wfm: 64 bins
    # Find minimum and N

for bin in wfm: 64 bins
    # Write compressed wfm
```

Goal

Take advantage of the huge number of GPU threads to parallelize for loops and minimize the number of iterations

Grid 1



Threads within the same block share very fast memory Grid size and block size are configurable within some limits

```
for wfm in packet: ~1e7 wfms per packet

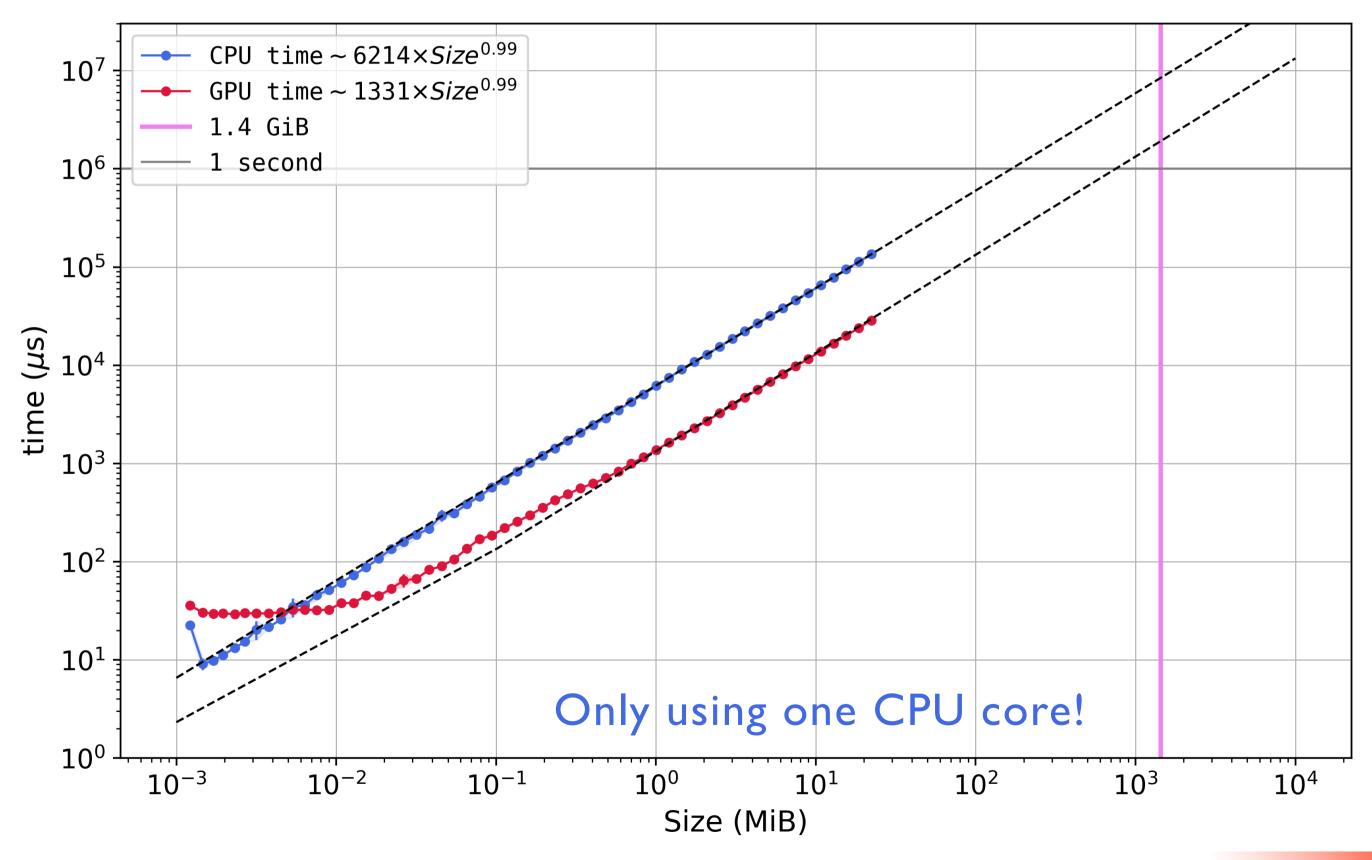
for bin in wfm:
    # Find minimum and N

for bin in wfm:
    # Write compressed wfm
```

- •Get rid of this loop by processing one waveform per thread
- Most of the code doesn't change

Results

At least a factor of 2 improvement needed on GPU At least a factor of 10 improvement needed on CPU



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Second step

Start re-designing the code for massive parallelism

```
• One block per waveform
• 64 threads per block

for bin in wfm: (next slide)

# Find minimum and N

for bin in wfm: (later)

# Write compressed wfm

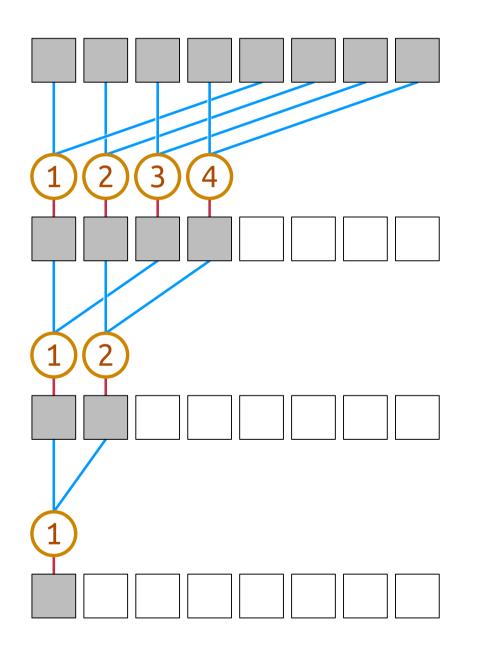
Re-write "Find maximum
in an array" on GPUs
```

How to find the max/min of an array of integers

Parallel reduction

Computation is fast

Needs to allocate extra memory

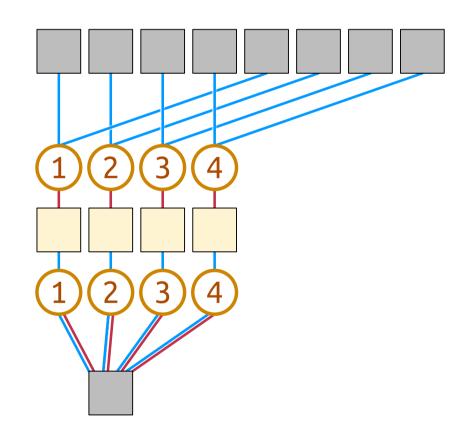


Method 2

...on a GPU

No extra memory required

Multiple threads write to the same address, so needs atomic operations



- 1 Thread (performs max() / min())
- Input
- Output

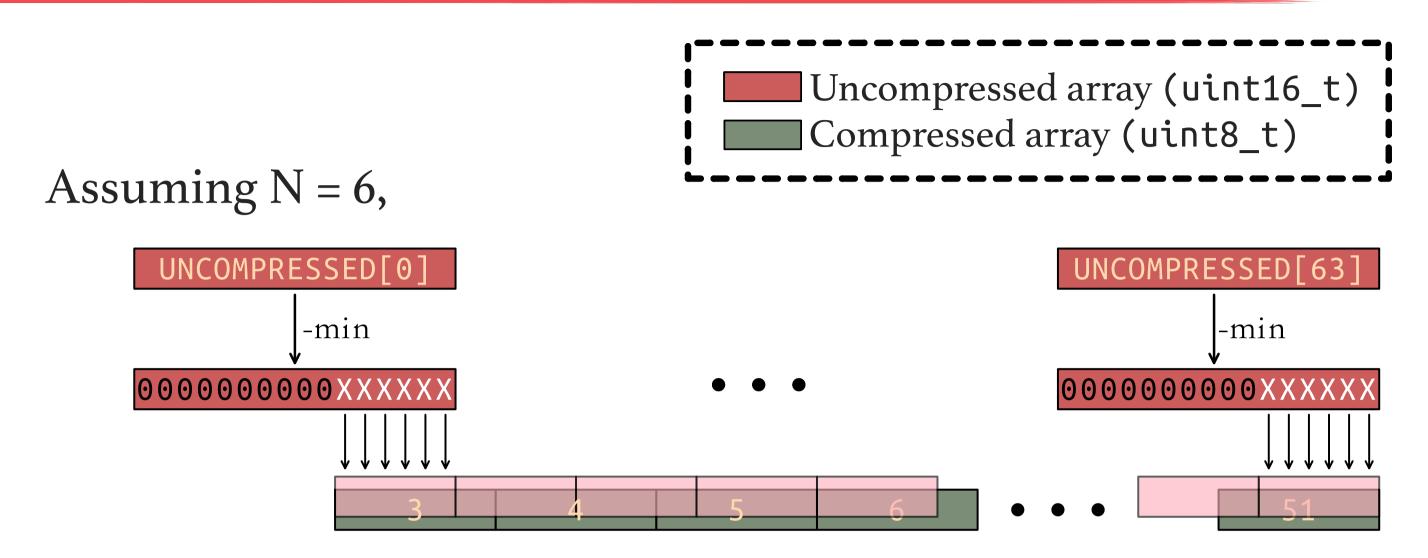
Parallelizing the compression

```
for wfm in packet:
    for bin in wfm:
        # Find N

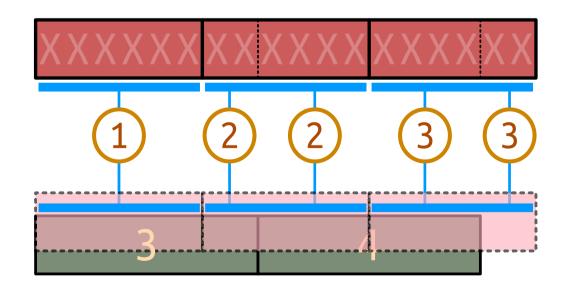
for bin in wfm:
    # Write compressed array
```

Write the compressed array in parallel

Parallelizing the compression



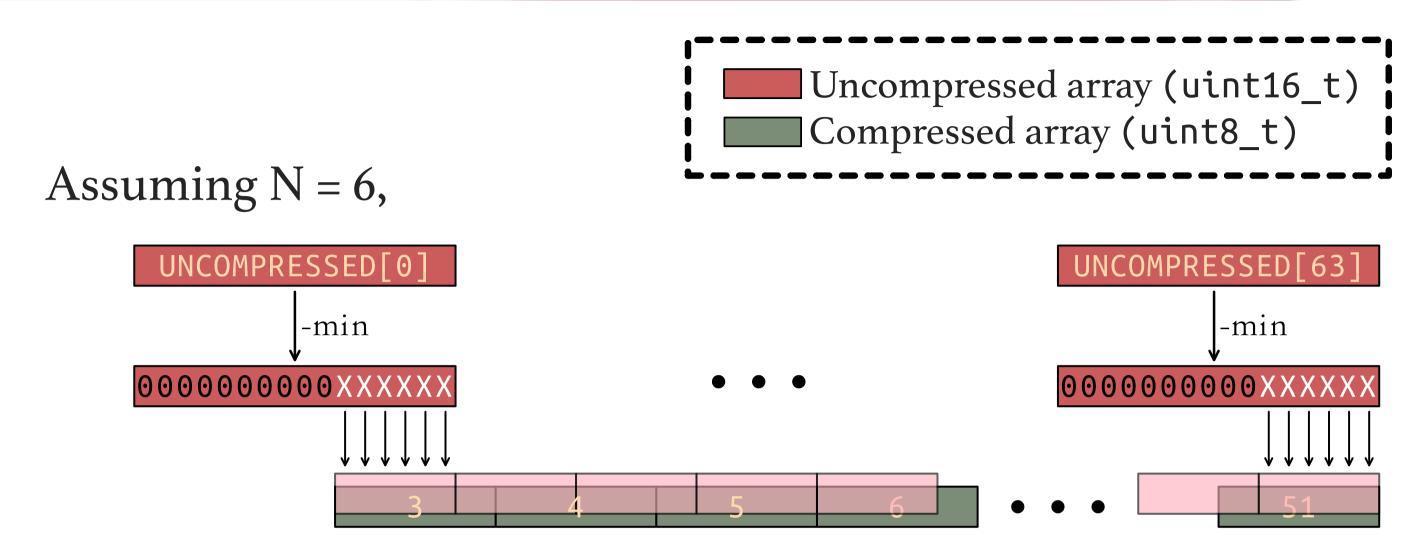
Option I: As many threads as waveform bins (red squares): 64



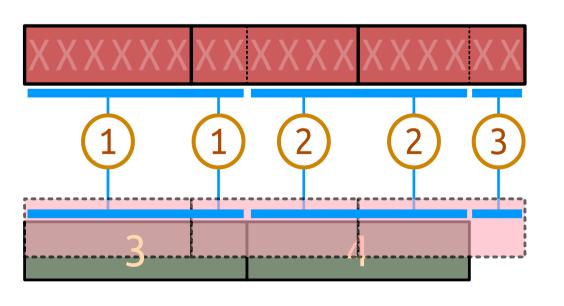
Every thread subtracts the minimum from one input element

Multiple threads write to the same address simultaneously, so atomic operations are needed

Parallelizing the compression



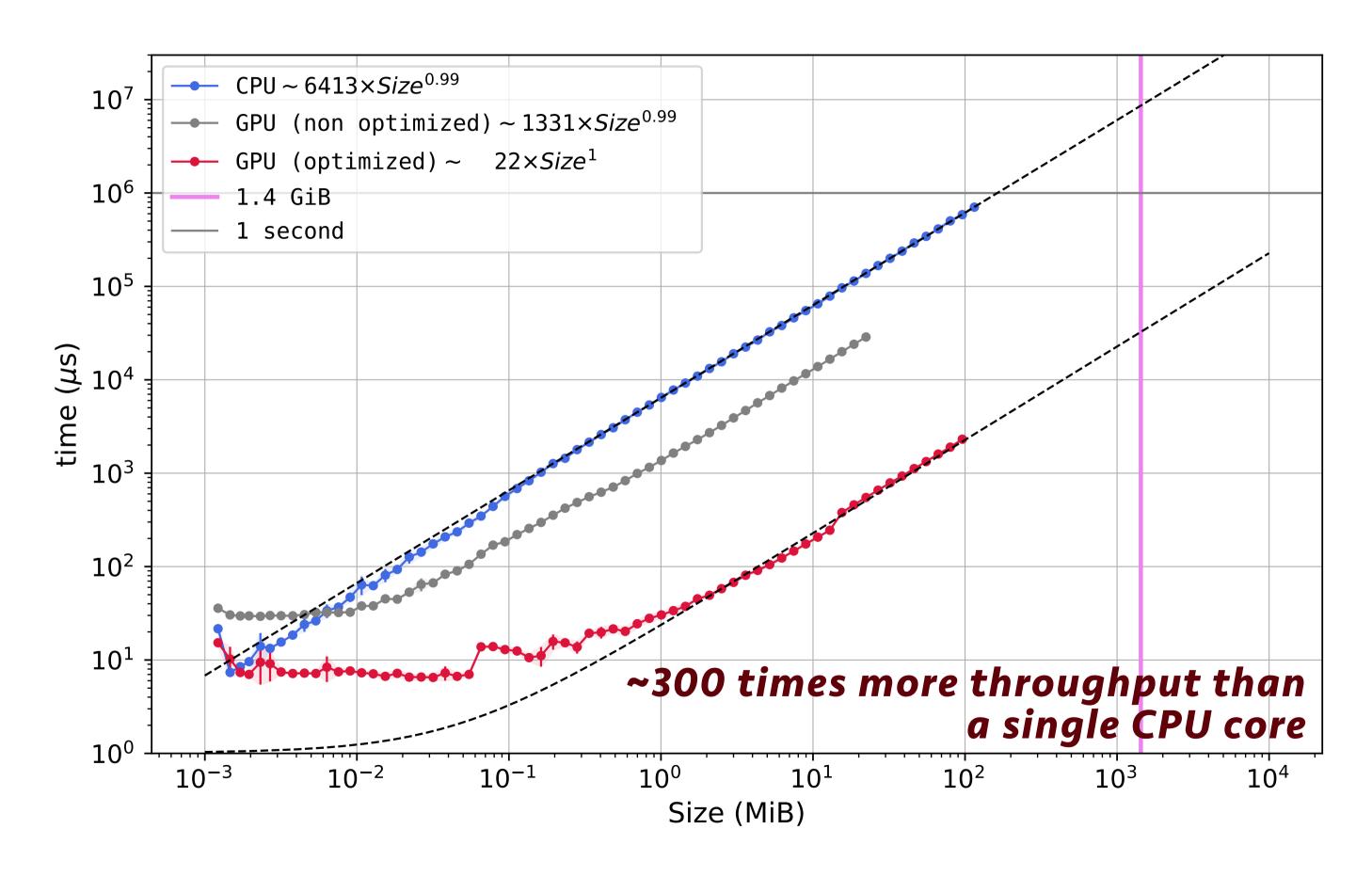
Option 2: As many threads as compressed bytes (green squares)



Fewer number of threads, since the compressed array has less bytes than the original

No write conflicts between threads, no atomic operations needed

Results



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28/10/21

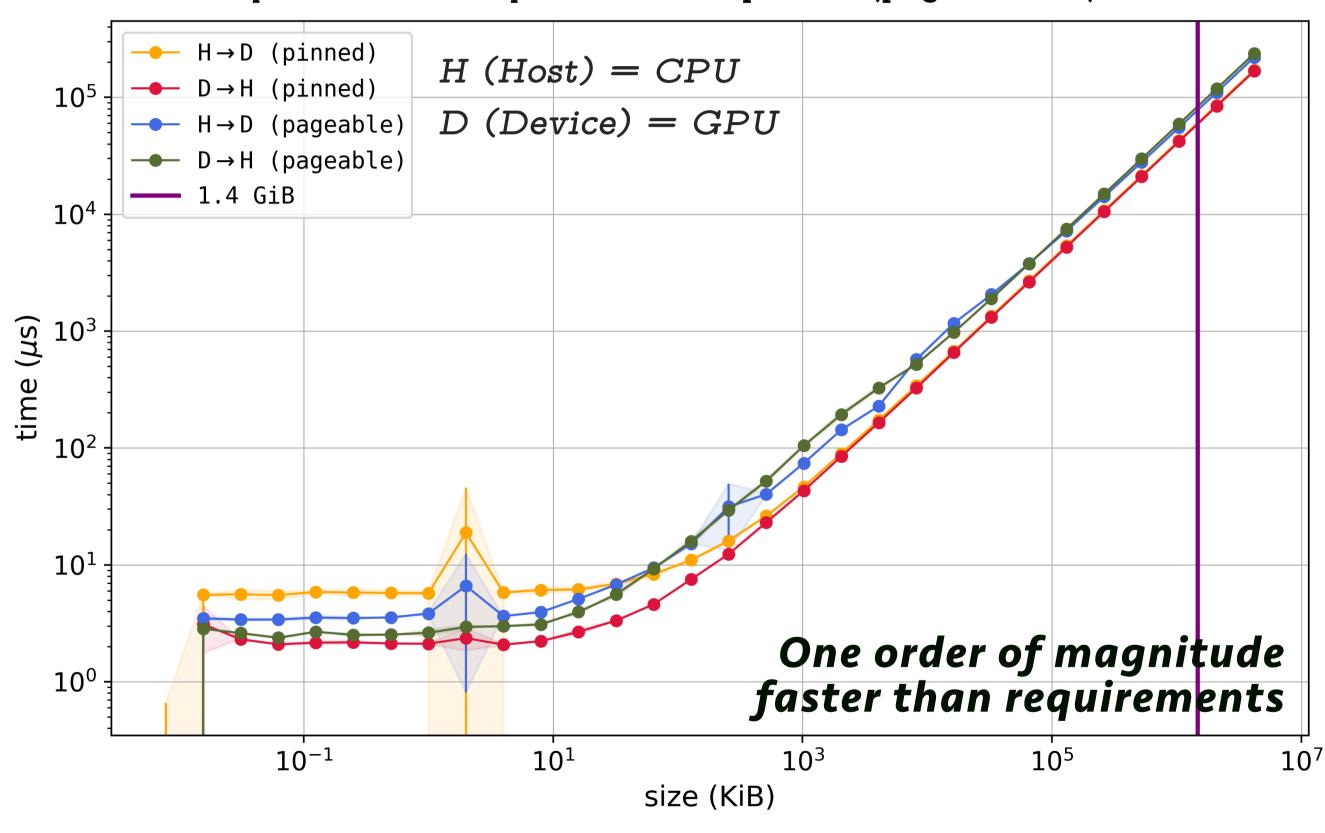
Checklist update

✓ •1s to compress 1.4 GiB

o 1 s to copy 1.4 GiB to/from the GPU

CPU-GPU data rates

Memory can be directly allocated as pinned (page-locked) in the host



Checklist update

✓ •1s to compress 1.4 GiB

✓ •1s to copy 1.4 GiB to/from the GPU

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GPUs have a great potential in HEP triggers and will be part of the future of KOTO

- One GPU can perform faster than a whole CPU server
- They are a lot smaller, cheaper and energetically efficient



Hardware

./deviceQuery Starting...

```
CUDA Device Query (Runtime API) version (CUDART static linking)
Detected 1 CUDA Capable device(s)
Device 0: "NVIDIA GeForce RTX 3060 Ti"
 CUDA Driver Version / Runtime Version
                                                 11.4 / 11.4
 CUDA Capability Major/Minor version number:
                                                 7980 MBytes (8367439872 bytes)
 Total amount of global memory:
 (038) Multiprocessors, (128) CUDA Cores/MP:
                                                4864 CUDA Cores
 GPU Max Clock rate:
                                                 1695 MHz (1.70 GHz)
 Memory Clock rate:
                                                 7001 Mhz
 Memory Bus Width:
                                                 256-bit
 L2 Cache Size:
                                                 3145728 bytes
 Maximum Texture Dimension Size (x,y,z)
                                                 1D=(131072), 2D=(131072, 65536), 3D=(16384, 16384, 16384)
 Maximum Layered 1D Texture Size, (num) layers 1D=(32768), 2048 layers
 Maximum Layered 2D Texture Size, (num) layers 2D=(32768, 32768), 2048 layers
 Total amount of constant memory:
                                                 65536 bytes
 Total amount of shared memory per block:
                                                 49152 bytes
 Total shared memory per multiprocessor:
                                                 102400 bytes
 Total number of registers available per block: 65536
 Warp size:
 Maximum number of threads per multiprocessor: 1536
 Maximum number of threads per block:
 Max dimension size of a thread block (x,y,z): (1024, 1024, 64)
 Max dimension size of a grid size (x,y,z): (2147483647, 65535, 65535)
 Maximum memory pitch:
                                                 2147483647 bytes
 Texture alignment:
                                                 512 bytes
                                                 Yes with 2 copy engine(s)
  Concurrent copy and kernel execution:
 Run time limit on kernels:
 Integrated GPU sharing Host Memory:
 Support host page-locked memory mapping:
                                                 Yes
 Alignment requirement for Surfaces:
                                                 Yes
 Device has ECC support:
                                                 Disabled
 Device supports Unified Addressing (UVA):
 Device supports Managed Memory:
                                                 Yes
 Device supports Compute Preemption:
                                                 Yes
 Supports Cooperative Kernel Launch:
 Supports MultiDevice Co-op Kernel Launch:
 Device PCI Domain ID / Bus ID / location ID:
                                                0 / 1 / 0
 Compute Mode:
    < Default (multiple host threads can use ::cudaSetDevice() with device simultaneously) >
deviceQuery, CUDA Driver = CUDART, CUDA Driver Version = 11.4, CUDA Runtime Version = 11.4, NumDevs = 1
Result = PASS
```

GPUNVIDIA GeForce RTX 3060 Ti

CPU
Intel(R) Core(TM)
i7-4770 CPU @ 3.40GHz