

解析・制御の統合プラットフォーム開発による
実験遂行能力の高度化

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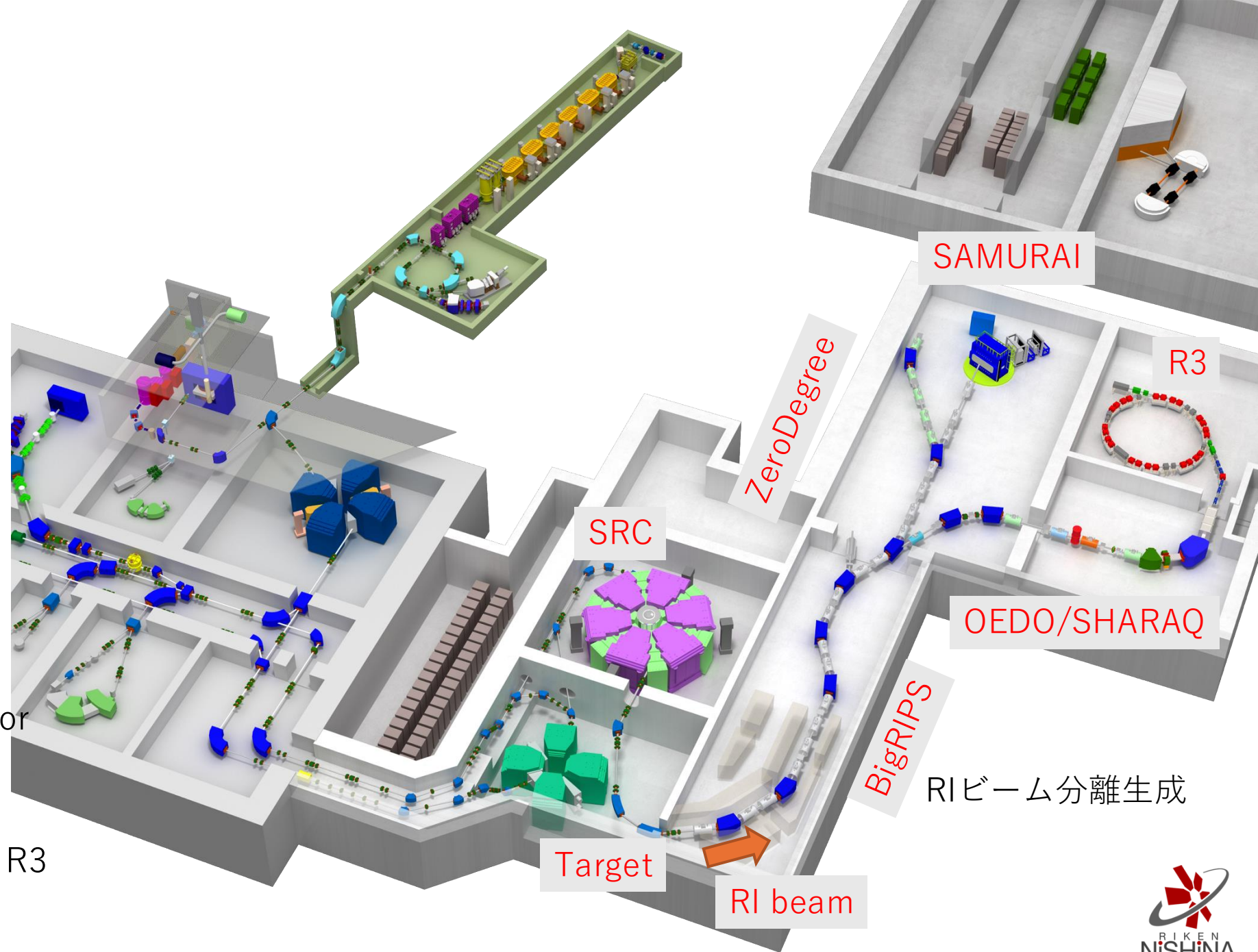
RI beam @ RIKEN RIBF

In-flight fragment separator

- BigRIPS

Spectrometer etc

- ZeroDegree, SAMURAI, R3
- OEDO/SHARAQ (CNS)

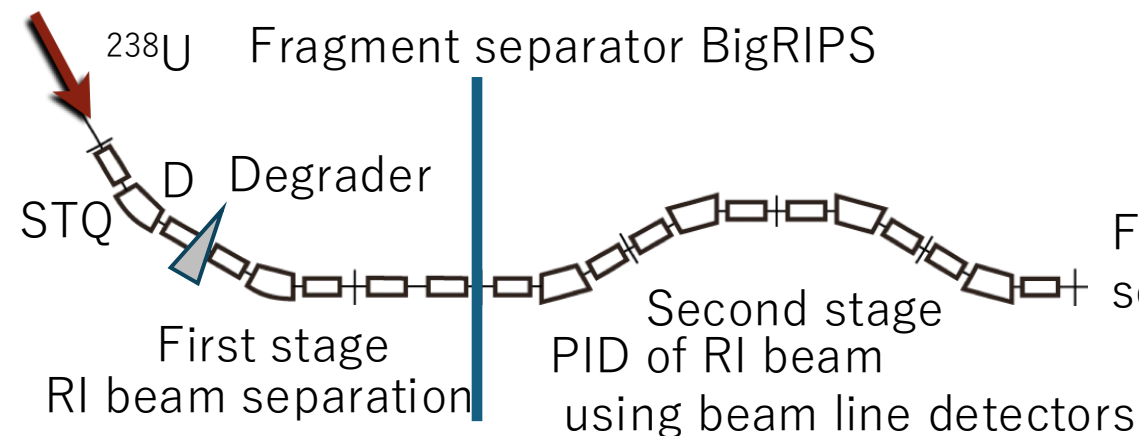
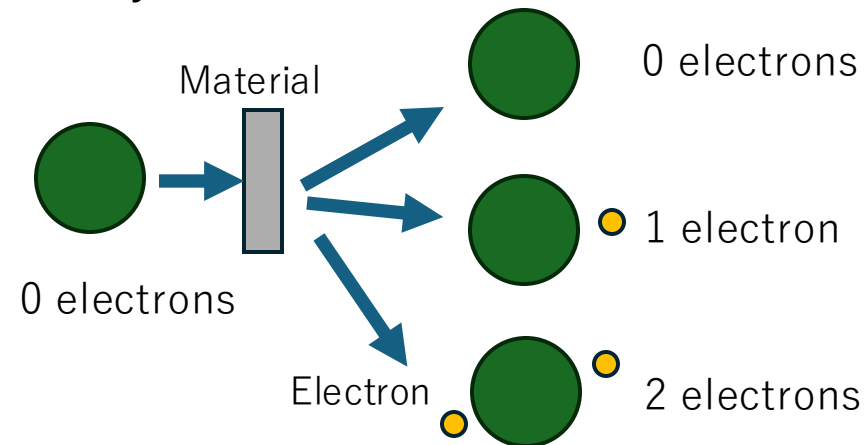


RIビーム分離生成

Improvement of RI-beam production at RIBF

- Issues about heavy RI beam
 - Charge state changes in beam-line materials.
 - Q change \rightarrow B ρ change
 - Complicating both the purification and PID of RI beam
- First development of heavy RI beam at RIBF

➤ Heavy-element RI beams



An unexpectedly large background of in-flight fission fragments

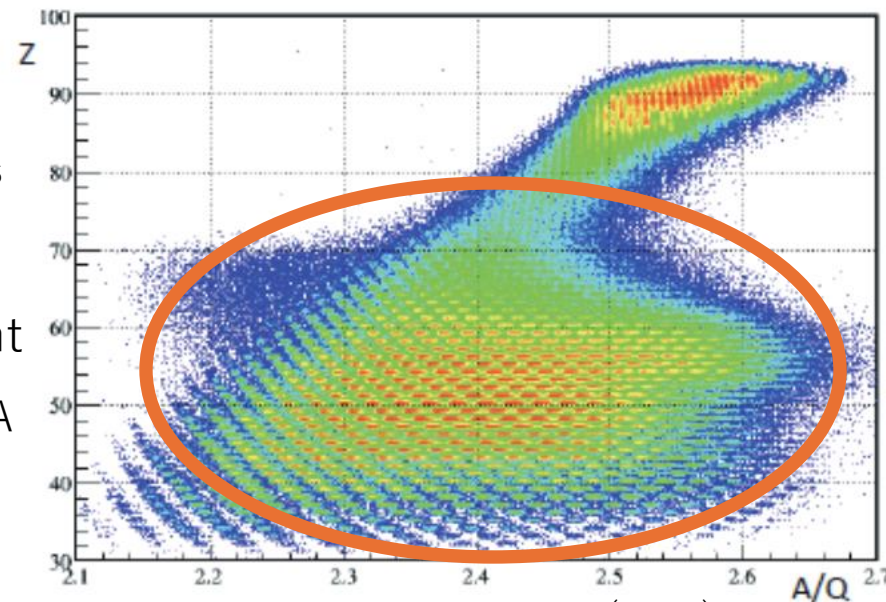
Found a practical solution after experiment

100 kHz/pnA

Should be solved online

Position: PPAC, Timing: Plastic, Diamond, Eloss: IC, γ ray: Ge

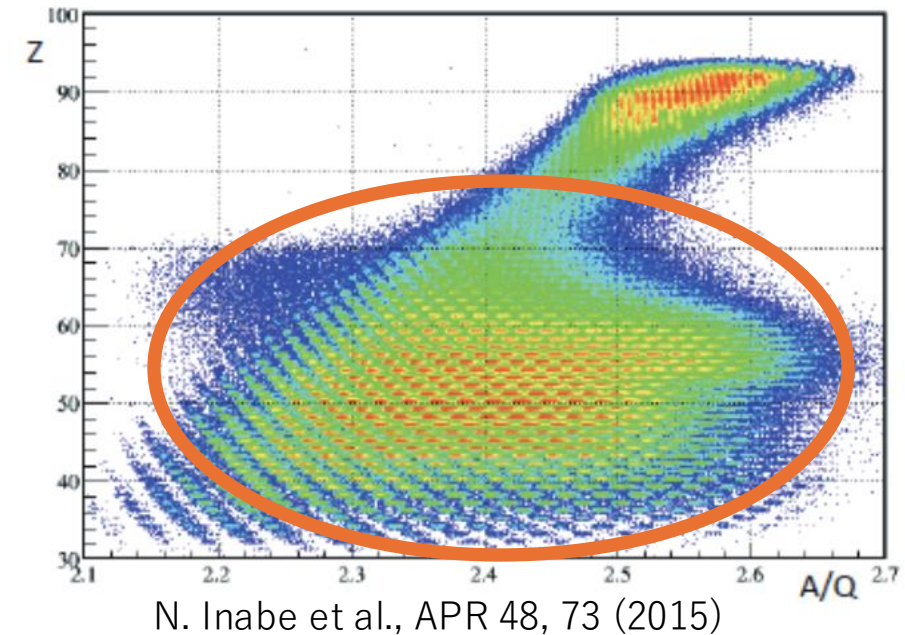
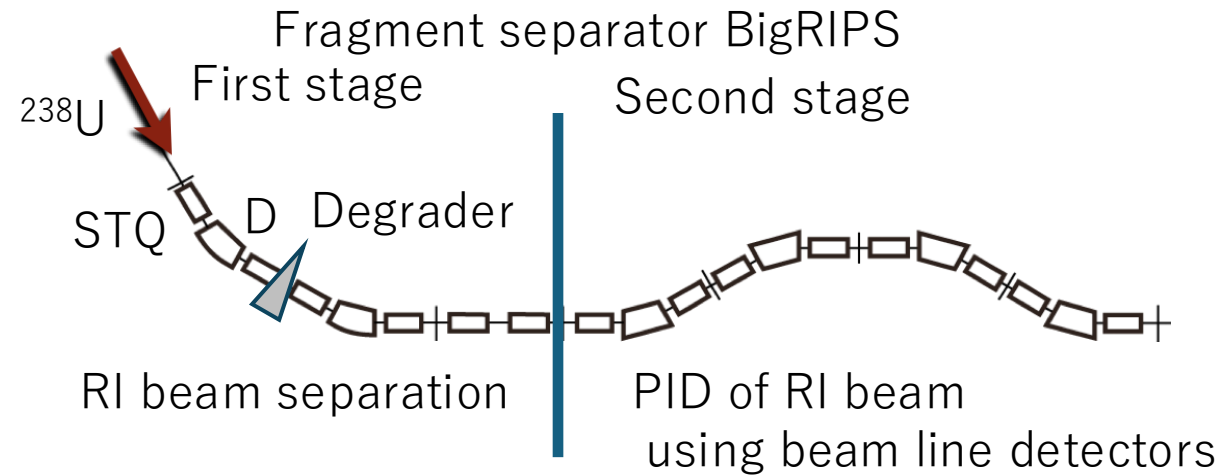
B ρ - ΔE - TOF \rightarrow Z, A/Q



N. Inabe et al., APR 48, 73 (2015)

Improvement of RI-beam production at RIBF

- **Demand for Speed & Quality:** Deliver RI beams *faster* and with *higher quality*.
- **Ideal: Real-Time Optimization:** Fully understand data & adjust BigRIPS.
- **The Reality: Highly Demanding.**
- **Growing Complexity:** More detectors = harder optimization.
- **The Question:** Do we have the right tools?
- **The Goal:** Enhance online capabilities.



Vision of integration platform BYACO

- Operate several tasks:
 - Data acquisition
 - Data analysis (histogram, fitting)
 - Magnet currents, detector setting etc.
 - Status monitoring
- Macro
 - Increase productivity
 - Not easy to handle all the matters involved
 - Many macros: Where is it? How to use it?

• BYACO

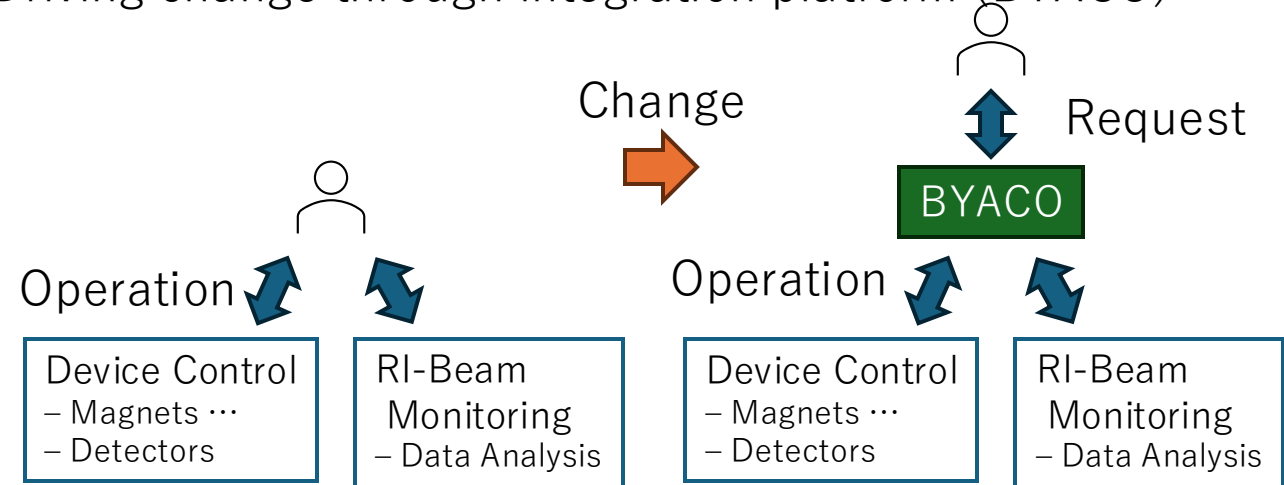
(BeYond Analysis, Control or Operation alone)

- Unifies all relevant controls into a single platform
- Established workflow
 - Executed by clicking a button in a Web application.

BYACO shifts the human role from routine operation to request.

We can focus on unexpected results and important things during experiment.

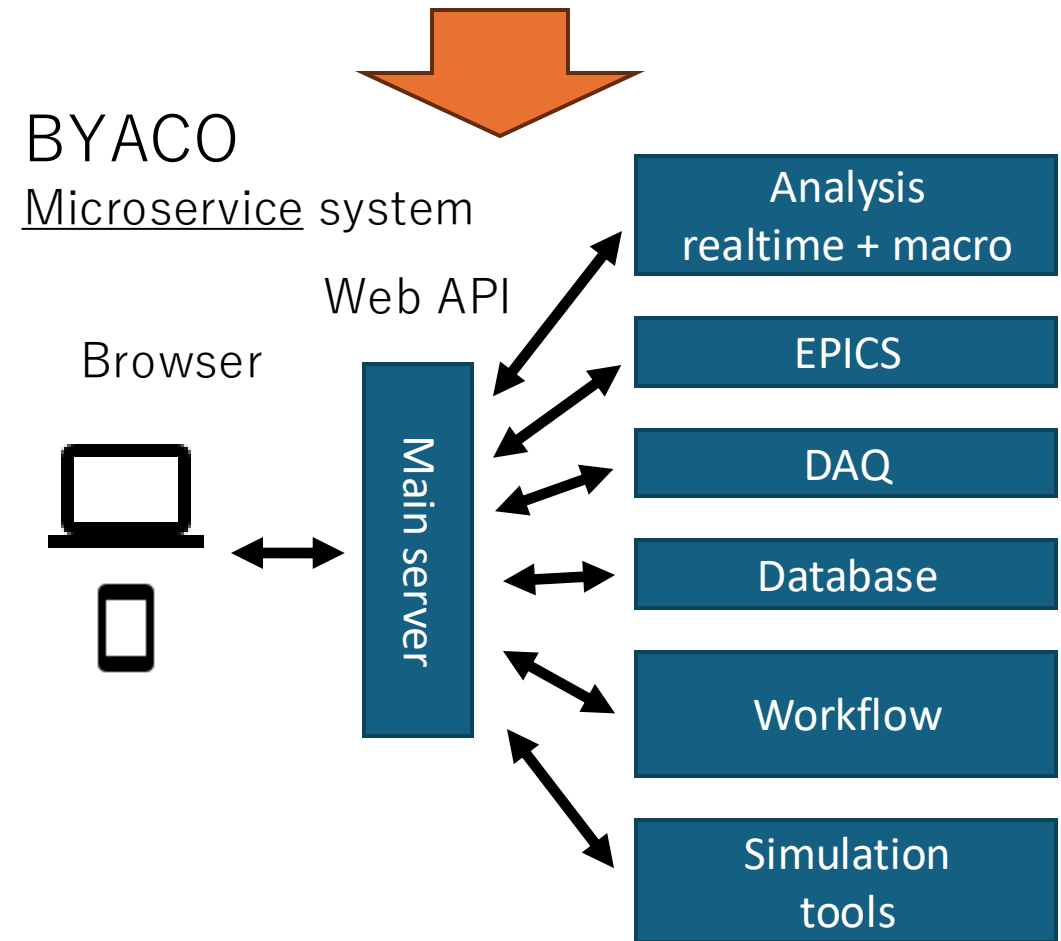
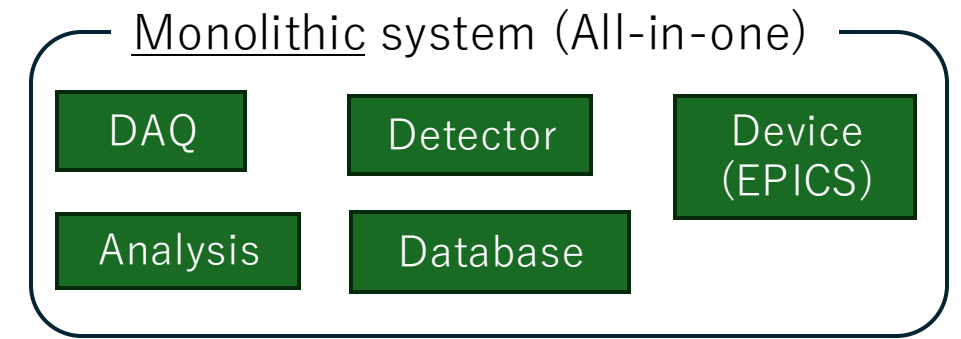
Driving change through integration platform (BYACO)



T. Sumikama et al., APR 54, 82 (2021).

Concept of BYACO

- BYACO: A platform combining multiple functions
 - Designed to advance online experiments, also adaptable to a wide range of use cases.
- Monolithic system
 - As the codebase grows, many components become tightly coupled and making changes slower over time.
 - Locked into a single technology stack.
- Microservice system (BYACO)
 - Loose coupling thorough Web APIs and sockets.
 - Web API (Command)
 - WebSocket (Information sharing)
 - Each component concentrates on a single function
 - Any languages can be used (e.g., C++, Python, JavaScript)
Note: Some libraries are language-specific.
- Integration of analysis software
 - macros developed for offline analysis



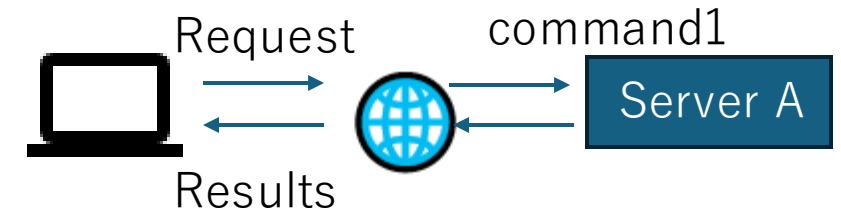
Exposing functionality via Web APIs

1. Use a library for Web server
 - Requires language-specific knowledge
2. Run a standalone program via StdIO
 1. Prepare a standalone program
 2. Modify a Node.js example to expose a Web API
 - This approach is very convenient and our favorite.

Web API

Web API in BYACO

<http://byaco.example.internal/serverA/command1>



Standard input/output

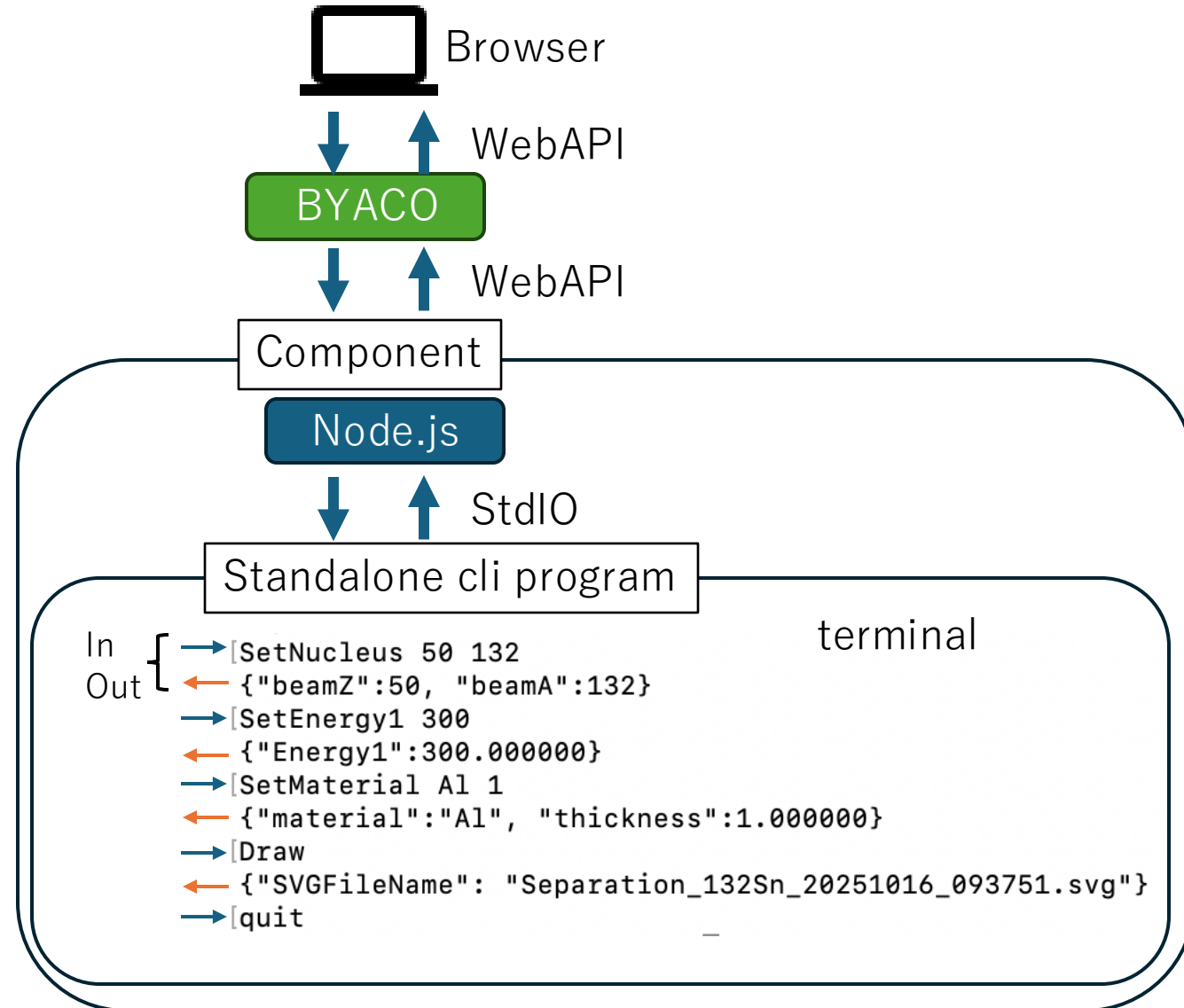
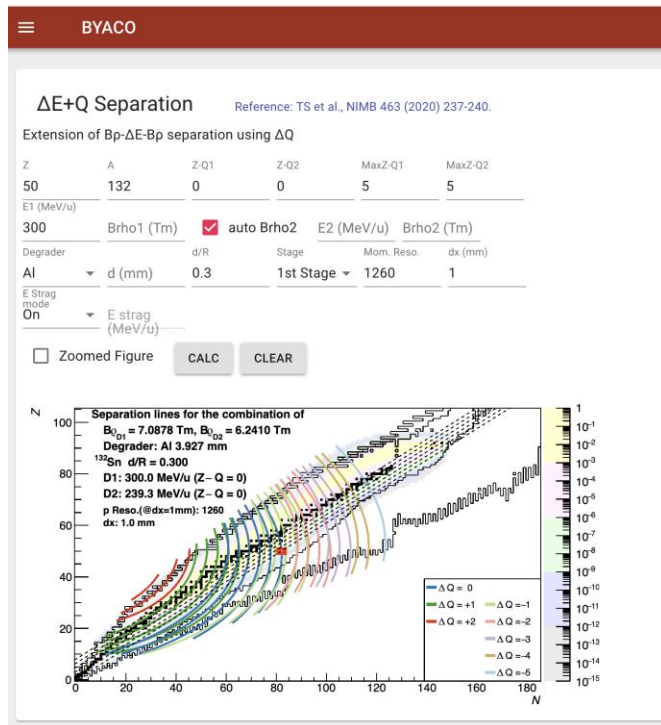
Fundamental interface

C++: cin/cout

Python: input/print

BYACO Use-Case: Running a simulation & fetching results via Web API

- Simple example
 - Isotope separation of fragment separator in case of Q change



BYACO Use-Cases

Developed by Shimizu-san

Total: about 20 cases

- Detector control

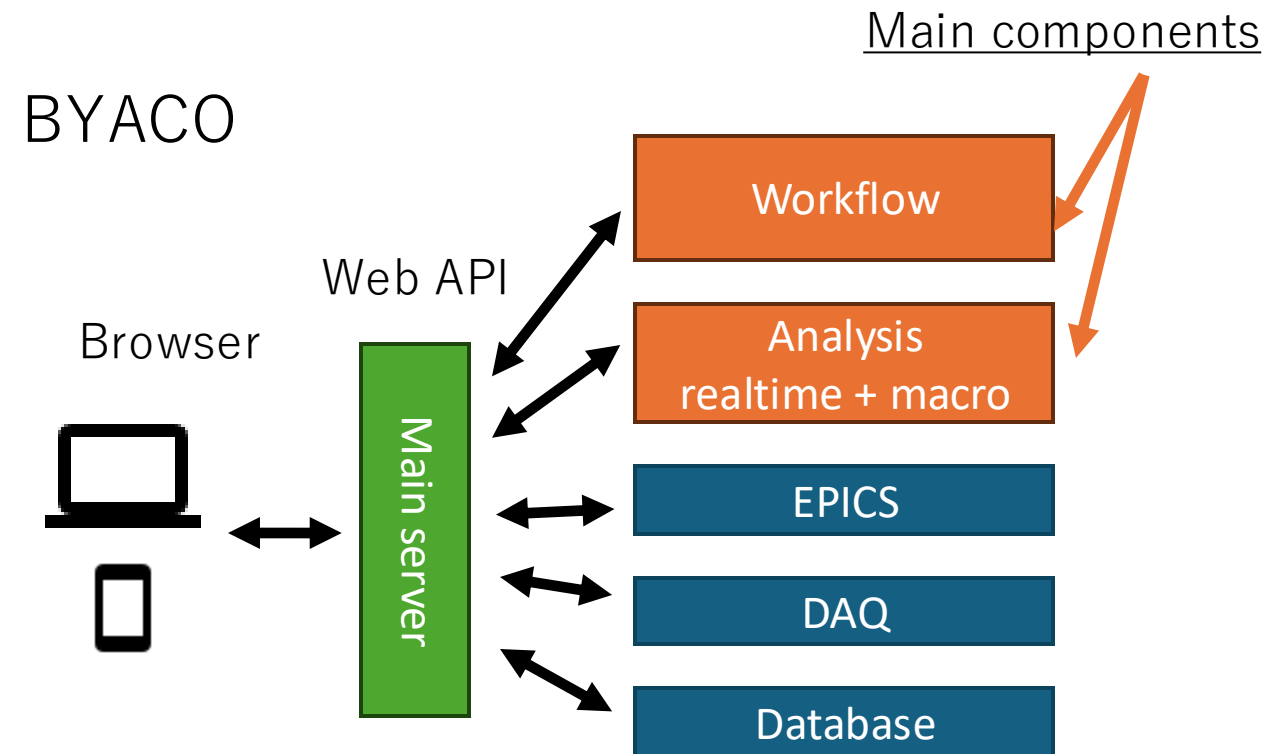
The screenshot shows a vertical navigation menu on the left side of the BYACO web interface. The menu items are: Home, Experiment, DAQ (with a dropdown arrow), Device (with an up arrow), PPAC HV, Pla HV, Gas Handler, Monitor Program (with a dropdown arrow), Automation Program (with a dropdown arrow), and Operation Tools (with a dropdown arrow). The main content area behind the menu is partially visible, showing the text 'igRIPS', 'BYACO', and 'eration alone (BYACO)'. A warning message is also visible: 'could affect online experiment' and 'of BigRIPS experiments.'.

The screenshot displays the 'BYACO for BigRIPS' web interface, specifically the 'PPAC HV Control' section. At the top, there are buttons for 'Print', 'Save', 'Load', 'All Set', 'All On', and 'All Off'. To the right, there are radio buttons for '1st' and '2nd', with '2nd' selected. Below these are four tabs: 'BigRIPS (F1~F7)', 'ZeroDegree (F8~F11)', 'SAMURAI (F8,F12)', and 'Trip Log'. The 'BigRIPS (F1~F7)' tab is active, showing a grid of control panels for various channels. Each panel includes a 'Set' button, a toggle switch, and a 'Reset' button. The data for each channel is as follows:

Channel	Current (µA)	Read (V)	Set (V)	Status
F1-1	0.468	-0.09	750.00	Off
F1-2	-0.437	-0.00	750.00	Off
F2-1	0.443	-0.10	730.00	Off
F2-2	0.420	-0.09	730.00	Off
F3-1A	0.218	-0.05	710.00	Off
F3-1B	0.207	-0.05	710.00	Off
F3-2A	0.209	-0.03	710.00	Off
F3-2B	0.226	-0.03	710.00	Off
F4	-0.153	-0.05	753.00	Off
F6	-0.213	-0.05	753.00	Off
F5-1A	0.216	-0.02	710.00	Off
F5-1B	0.160	-0.03	710.00	Off
F5-2A	-0.125	-0.03	710.00	Off
F5-2B	0.091	-0.02	710.00	Off
F7-1A	0.181	-0.04	710.00	Off
F7-1B	0.177	-0.04	710.00	Off
F7-2A	0.253	-0.05	710.00	Off
F7-2B	-0.212	-0.03	710.00	Off

BYACO Use-Case: Automated RI-beam tuning

- Component Design
 - Separate Concerns
 - **Analysis** – applies gates to measured data, perform curve fitting
 - **Workflow Orchestrator** – builds and drives the beam-tuning sequence.
 - Isolate External Interfaces
 - EPICS Interface
 - DAQ Interface
 - Database Interface



Analysis software with ROOT-based GUI

- Most challenging component

- Begin with a minimal PoC for automated RI-beam tuning
- Three sub-components

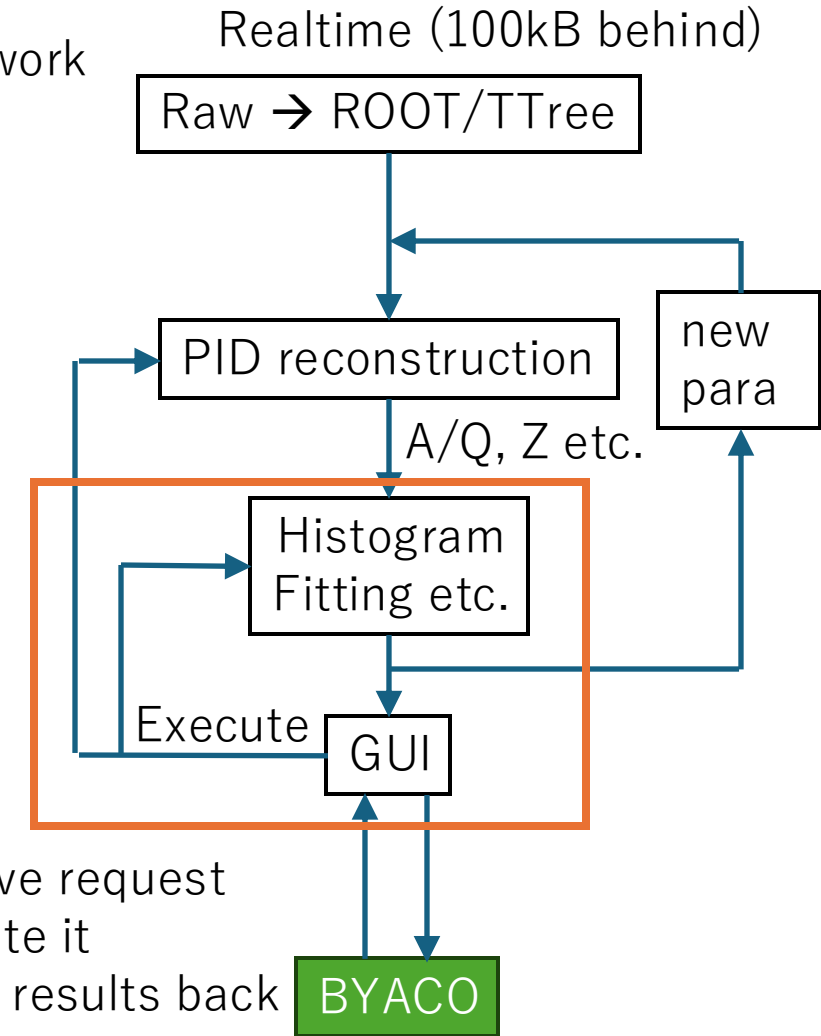
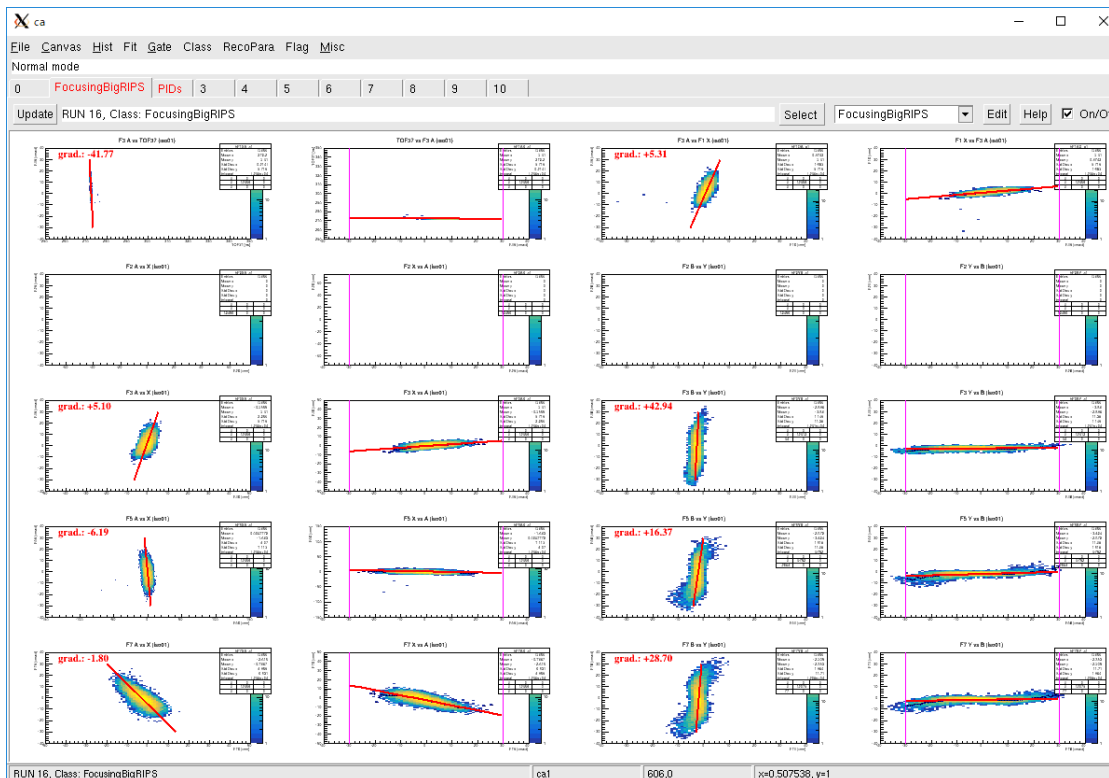
GUI application

Leverage ROOT's built-in GUI framework

- Histogram filling + fitting etc.

One tab → One file (PROOF-lite)

- Communication with BYACO



Analysis software with ROOT-based GUI

- Example

Event loop

```
Bool_t FocusingBigRIPS::Process(Long64_t entry)
{
    // The Process() function is called for each entry in the

    if(key.size()==0) return kTRUE;
    fReader.SetLocalEntry(entry);
    if( useflag && !(*flagAll) ){ return kTRUE; }
    if( !IsInside(iso01) ){ return kTRUE; }

    f2x = (*F2X) + f2z * (*F2A) / 1000.;
    f2y = (*F2Y) + f2z * (*F2B) / 1000.;

    f3x = (*F3X) + f3z * (*F3A) / 1000.;
    f3y = (*F3Y) + f3z * (*F3B) / 1000.;

    f5x = (*F5X) + f5z * (*F5A) / 1000.;
    f5y = (*F5Y) + f5z * (*F5B) / 1000.;

    f7x = (*F7X) + f7z * (*F7A) / 1000.;
    f7y = (*F7Y) + f7z * (*F7B) / 1000.;

    // user area
    hF1XA->Fill(*T0F37,*F3A);
    hF1AX->Fill(*F3A,*T0F37);
    hF2XA->Fill(f2x,*F2A);
    hF2YB->Fill(f2y,*F2B);
    hF2AX->Fill(*F2A,f2x);
    hF2BY->Fill(*F2B,f2y);
    hF3XA->Fill(f3x,*F3A);
    hF3YB->Fill(f3y,*F3B);
}
```

- Programming in C++

- Merit: Flexible
- Demerit: Take a lot of effort
 - Use GUI for simple figures and operations
 - ROOT GUI: End of development

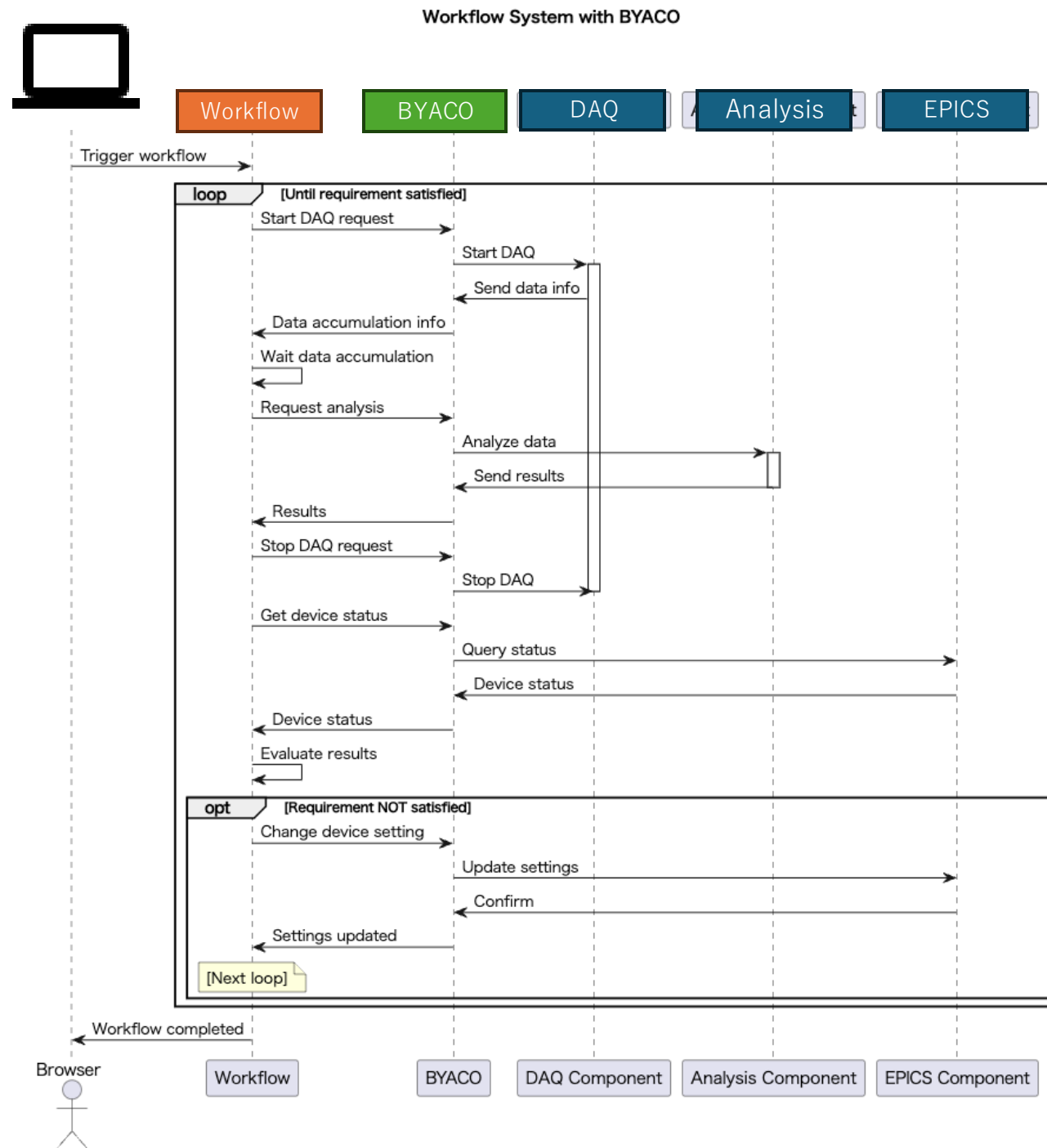
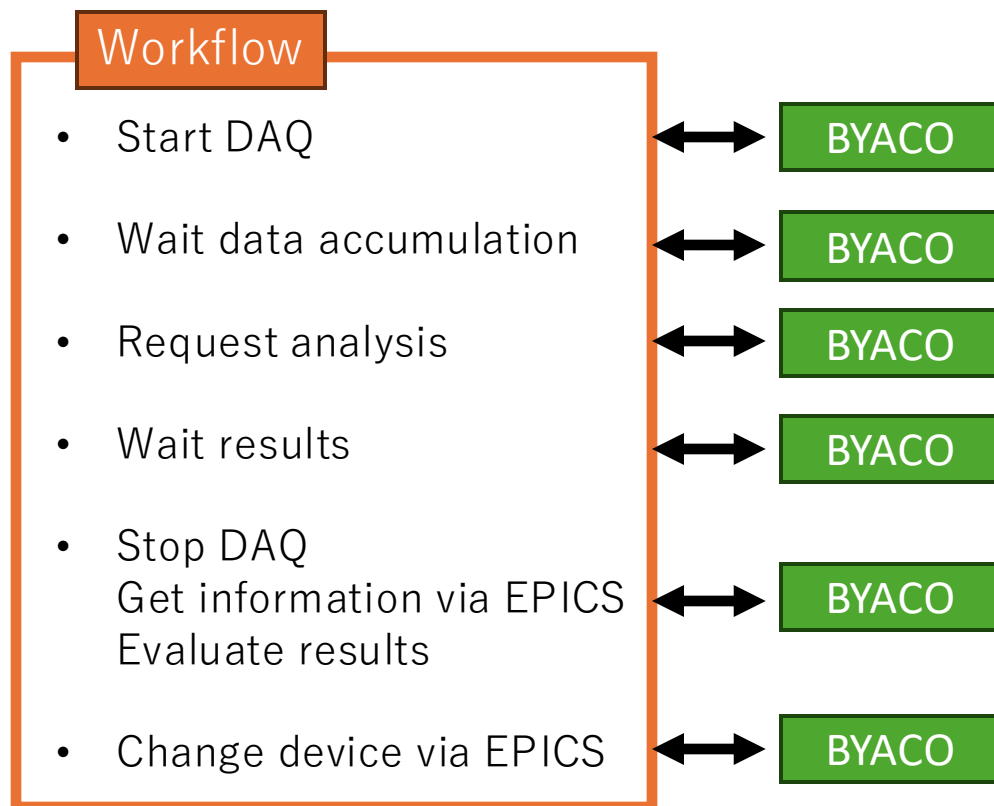
After event loop

```
void FocusingBigRIPS::Terminate()
{
    grad->SetText(kRed);

    c->cd(1); hF1XA->Draw("colz"); SetLogz(hF1XA, gPad);
    c->cd(2);
    if( hF1AX->GetEffectiveEntries() > detectionlimit && gf3a.grmin && gf3a.grmax )
        hF1AX->GetXaxis()->SetRangeUser(gf3a.GetMin(),gf3a.GetMax());
    if( hF1AX->GetEffectiveEntries() > detectionlimit ){
        r = hF1AX->Fit("pol1","SQ");
        c->cd(1);
        res->DrawLine(r->Parameter(1)*gf3a.GetMin()+r->Parameter(0),gf3a.GetMax(),gf3a.GetMin());
        grad->DrawLatexNDC(0.15,0.84,Form("grad.: %+.2f", 1/r->Parameter(1)));
        c->cd(2);
    }
    hF1AX->GetXaxis()->UnZoom();
}
hF1AX->Draw("colz"); SetLogz(hF1AX, gPad); gf3a.Draw();
}
```

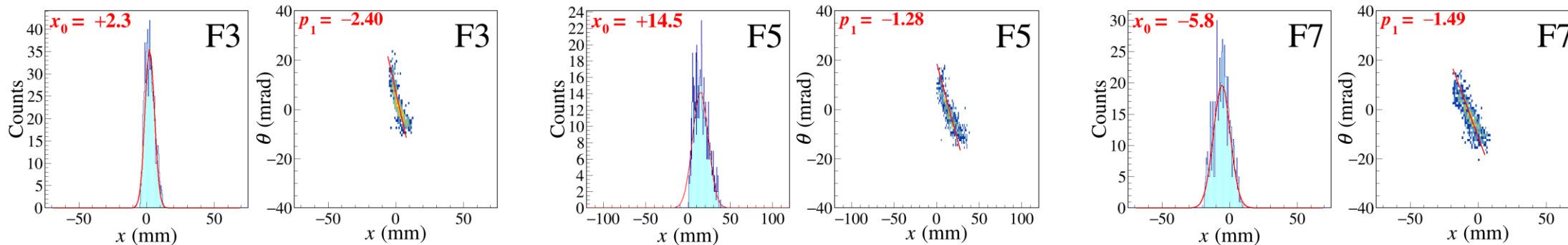
Workflow orchestrator

- Workflow communicates with BYACO main server, forwarding requests to each server.

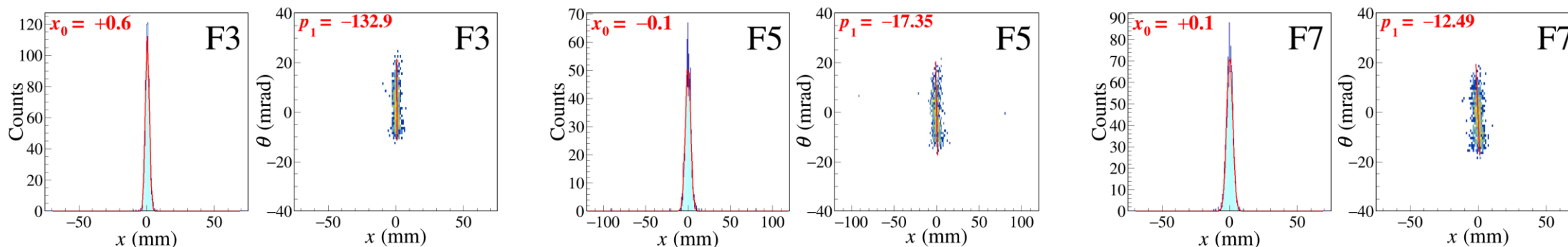


Experimental demonstration Automated focusing & centering

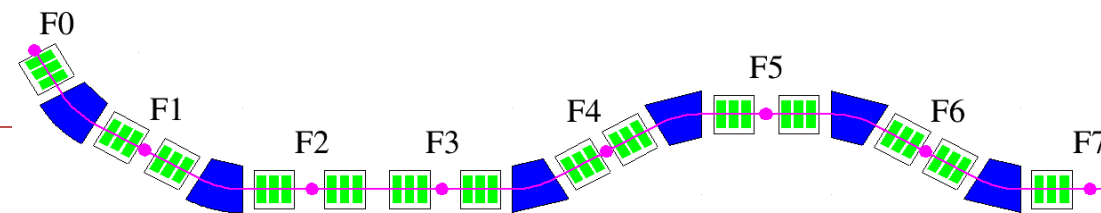
before automated focusing & centering



after automated focusing & centering



Successfully demonstrated automated focus tuning using BYACO.



Perspective

- Issues identified in the PoC

- Analysis:

RI beams with different Z, A, and E
Different detector responses
Different sources of contaminant RI beams

Before a final RI-beam tuning, we need a detector optimization, rough RI-beam purification and rough RI-beam tuning.

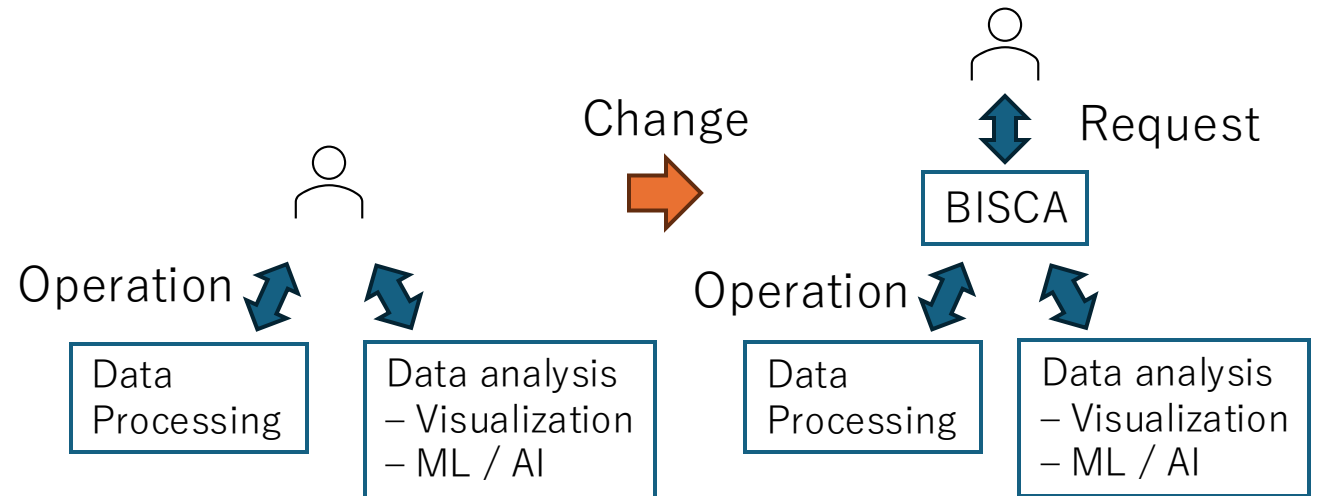
Analysis software needs to cover these processes and customizations for automation.

Need flexibility and interactivity.

- Future development

1. New analysis software

- Bring Inspired Sense and Creativity to Analyst (BISCA)



- Modern visualization with flexibility and interactivity
- AI, ML, generative AI

Under conceptual design

Perspective

- Issues identified in the PoC
 - Workflow:
Use of dedicated OSS
 - Secure Usability:
Authentication & Authorization
 - Operations:
Managing an expanding micro-service ecosystem

- Future development
 2. Build a Kubernetes cluster for microservices
 - Accelerate migration to a fully containerized stack
 - Enable Kubernetes-native OSS for future integration of AI/ML tools



Summary

- **BYACO is an integration platform** for analysis, control, and operation in RI beam experiments.
- **Microservice architecture** promotes flexibility, scalability, and integration of diverse tools & program languages.
- **Decoupled components & Web API communication** enable automated workflows.
- **Successful demonstration of automated beam tuning** validates the core concepts.
- **Future Development:** Expanding analysis software, dedicated OSS workflow, etc.